

INVARIANT GENERALIZED FUNCTIONS ON $\mathfrak{sl}(2, \mathbb{R})$ WITH VALUES IN A $\mathfrak{sl}(2, \mathbb{R})$ -MODULE

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ABSTRACT. Let \mathfrak{g} be a finite dimensional real Lie algebra. Let $\rho : \mathfrak{g} \rightarrow \text{End}(V)$ be a representation of \mathfrak{g} in a finite dimensional real vector space. Let $\mathcal{C}_V = (\text{End}(V) \otimes S(\mathfrak{g}))^{\mathfrak{g}}$ be the algebra of $\text{End}(V)$ -valued invariant differential operators with constant coefficients on \mathfrak{g} . Let \mathcal{U} be an open subset of \mathfrak{g} . We consider the problem of determining the space of generalized functions ϕ on \mathcal{U} with values in V which are locally invariant and such that $\mathcal{C}_V \phi$ is finite dimensional.

In this article we consider the case $\mathfrak{g} = \mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{N} be the nilpotent cone of $\mathfrak{sl}(2, \mathbb{R})$. We prove that when \mathcal{U} is $SL(2, \mathbb{R})$ -invariant, then ϕ is determined by its restriction to $\mathcal{U} \setminus \mathcal{N}$ where ϕ is analytic (cf. Theorem 6.1). In general this is false when \mathcal{U} is not $SL(2, \mathbb{R})$ -invariant and V is not trivial. Moreover, when V is not trivial, ϕ is not always locally L^1 . Thus, this case is different and more complicated than the situation considered by Harish-Chandra (cf. [HC64, HC65]) where \mathfrak{g} is reductive and V is trivial.

To solve this problem we find all the locally invariant generalized functions supported in the nilpotent cone \mathcal{N} . We do this locally in a neighborhood of a nilpotent element Z of \mathfrak{g} (cf. Theorem 4.1) and on an $SL(2, \mathbb{R})$ -invariant open subset $\mathcal{U} \subset \mathfrak{sl}(2, \mathbb{R})$ (cf. Theorem 4.2). Finally, we also give an application of our main theorem to the Superpfaffian (cf. [Lav04]).

1. INTRODUCTION

Let \mathfrak{g} be a finite dimensional real Lie algebra. Let $\rho : \mathfrak{g} \rightarrow \text{End}(V)$ be a representation of \mathfrak{g} in a finite dimensional real vector space. Let $\mathcal{C}_V = (\text{End}(V) \otimes S(\mathfrak{g}))^{\mathfrak{g}}$ be the algebra of $\text{End}(V)$ -valued invariant differential operators with constant coefficients on \mathfrak{g} . It is the *classical family algebra* in the terminology of Kirillov (cf. [Kir00]). Let \mathcal{U} be an open subset of \mathfrak{g} . We consider the problem of determining the space of generalized functions ϕ on \mathcal{U} with values in V which are locally invariant and such that $\mathcal{C}_V \phi$ is finite dimensional.

When $V = \mathbb{R}$ is the trivial module and \mathfrak{g} is reductive, the problem was solved by Harish-Chandra (cf. in particular [HC64, HC65]). Let ϕ be a locally invariant generalized function such that $S(\mathfrak{g})^{\mathfrak{g}} \phi$ is finite dimensional. He proved that ϕ is locally L^1 , ϕ is determined by its restriction $\phi|_{\mathfrak{g}'}$ to the open subset \mathfrak{g}' of semi-simple regular elements of \mathfrak{g} and $\phi|_{\mathfrak{g}'}$ is analytic.

In this article we consider the case $\mathfrak{g} = \mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{N} be the nilpotent cone of $\mathfrak{sl}(2, \mathbb{R})$. In this case $\mathfrak{g}' = \mathfrak{sl}(2, \mathbb{R}) \setminus \mathcal{N}$. Let ϕ be a locally invariant generalized function on \mathcal{U} with values in V such that $\mathcal{C}_V \phi$ is finite dimensional. We prove that when \mathcal{U} is $SL(2, \mathbb{R})$ -invariant, then ϕ is determined by its restriction to $\mathcal{U} \setminus \mathcal{N}$ where ϕ is analytic (cf. Theorem 6.1). In general this is false when \mathcal{U} is not $SL(2, \mathbb{R})$ -invariant and V is not trivial. Moreover, when V is not trivial, ϕ is not always locally L^1 . Finally, we also give an application of our main theorem to the Superpfaffian (cf. [Lav04]).

To solve the problem we find all the locally invariant generalized functions supported in the nilpotent cone \mathcal{N} . Let V_n be the $n+1$ -dimensional irreducible representation of $\mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{U} be an open subset of $\mathfrak{sl}(2, \mathbb{R})$. We denote by $\mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})}$ the set of locally invariant generalized functions on \mathcal{U} with values in V_n . Let \square be the Casimir operator on \mathfrak{g} .

We denote by \mathcal{N}^+ (resp. \mathcal{N}^-) the “upper” (resp. “lower”) half nilpotent cone (cf. 4.1). We put:

$$\begin{aligned} (1) \quad \mathcal{S}_n^0(\mathcal{U}) &= \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus \{0\}} = 0\}; \\ (2) \quad \mathcal{S}_n^\pm(\mathcal{U}) &= \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus (\mathcal{N}^\pm \cup \{0\})} = 0\}; \\ (3) \quad \mathcal{S}_n(\mathcal{U}) &= \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus \mathcal{N}} = 0\}. \end{aligned}$$

Let $Z \in \mathcal{N}^+$. We assume that \mathcal{U} is a suitable open neighborhood of Z (cf. section 4.6). Let $\delta_{\mathcal{N}^\pm}$ be an invariant generalized function with support $\mathcal{N}^\pm \cup \{0\}$ (cf. section 4.4). We construct an invariant function s_n on $\mathcal{N} \cap \mathcal{U}$ with values in V_n . We prove (cf. Theorem 4.1):

(i) When n is even, $\mathcal{S}_n(\mathcal{U})$ is an infinite dimensional vector space with basis:

$$(4) \quad (\square^k(s_n \delta_{\mathcal{N}^+}))_{k \in \mathbb{N}}.$$

(ii) When n is odd, $\dim(\mathcal{S}_n(\mathcal{U})) = \frac{n+1}{2}$ and a basis is given by:

$$(5) \quad (\square^k(s_n \delta_{\mathcal{N}^+}))_{0 \leq k \leq \frac{n-1}{2}}.$$

We assume that \mathcal{U} is an $SL(2, \mathbb{R})$ -invariant open subset of $\mathfrak{sl}(2, \mathbb{R})$. If $\mathcal{U} \cap \mathcal{N} \neq \emptyset$, we have $\mathcal{N}^+ \subset \mathcal{U}$ or $\mathcal{N}^- \subset \mathcal{U}$. We prove (cf. Theorem 4.2):

(i)

$$(6) \quad \begin{cases} \mathcal{S}_n^0(\mathcal{U}) = \{0\} & \text{if } 0 \notin \mathcal{U}; \\ \mathcal{S}_n^0(\mathcal{U}) \simeq (V_n \otimes S(\mathfrak{sl}(2, \mathbb{R})))^{\mathfrak{sl}(2, \mathbb{R})} & \text{if } 0 \in \mathcal{U}. \end{cases}$$

(ii) When n is even, we have:

$$(7) \quad \mathcal{S}_n(\mathcal{U}) = \mathcal{S}_n^0(\mathcal{U}) \oplus \text{Vect}\{\square^k(s_n \delta_{\mathcal{N}^+})|_{\mathcal{U}} / k \in \mathbb{N}\} \oplus \text{Vect}\{\square^k(s_n \delta_{\mathcal{N}^-})|_{\mathcal{U}} / k \in \mathbb{N}\}$$

$$(8) \quad \mathcal{S}_n^\pm(\mathcal{U}) = \mathcal{S}_n^0(\mathcal{U}) \oplus \text{Vect}\{\square^k(s_n \delta_{\mathcal{N}^\pm})|_{\mathcal{U}} / k \in \mathbb{N}\}$$

(iii) When n is odd:

$$(9) \quad \mathcal{S}_n(\mathcal{U}) = \mathcal{S}_n^\pm(\mathcal{U}) = \mathcal{S}_n^0(\mathcal{U})$$

Finally, let \mathcal{U} be an open subset of $\mathfrak{sl}(2, \mathbb{R})$. Let V be the space of a real finite dimensional representation of \mathfrak{g} . Let ϕ be an invariant function defined on \mathcal{U} such that $\mathcal{C}_V \phi$ is finite dimensional. This last condition is equivalent to the existence of $r \in \mathbb{N}$ and $(a_0, \dots, a_{r-1}) \in \mathbb{R}^r$ such that:

$$\left(\square^r + \sum_{k=0}^{r-1} a_k \square^k \right) \phi = 0.$$

Moreover, we assume that $\phi|_{\mathcal{U} \setminus \mathcal{N}} = 0$. We prove (cf. Theorem 5.3) that if \mathcal{U} is $SL(2, \mathbb{R})$ -invariant, then we have $\phi = 0$.

In general, when \mathcal{U} is not $SL(2, \mathbb{R})$ -invariant, there exist non trivial solutions of the equation $\square^k \phi = 0$ which are supported in the nilpotent cone (cf. Theorem 5.2).

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2. NOTATIONS

Let \mathfrak{g} be a finite dimensional real Lie algebra. Let $\rho : \mathfrak{g} \rightarrow \text{End}(V)$ be a representation of \mathfrak{g} in a finite dimensional real vector space V . Let \mathcal{U} be an open subset of \mathfrak{g} . We denote by $\mathcal{D}_c^\infty(\mathcal{U})$ the space of compactly supported smooth densities on \mathcal{U} . We put:

$$(10) \quad \mathcal{C}^{-\infty}(\mathcal{U}, V) = \mathcal{L}(\mathcal{D}_c^\infty(\mathcal{U}), V),$$

where \mathcal{L} stands for continuous homomorphisms. It is the space of generalized functions on \mathcal{U} with values in V . We put $\mathcal{C}^{-\infty}(\mathcal{U}) = \mathcal{C}^{-\infty}(\mathcal{U}, \mathbb{R})$. For $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)$ and $\mu \in \mathcal{D}_c^\infty(\mathcal{U})$, we denote by:

$$(11) \quad \int_{\mathcal{U}} \phi(Z) d\mu(Z)$$

the image of μ by ϕ . We have:

$$(12) \quad \mathcal{C}^{-\infty}(\mathcal{U}, V) = \mathcal{C}^{-\infty}(\mathcal{U}) \otimes V$$

(we will also write ϕv for $\phi \otimes v$).

Let $Z \in \mathfrak{g}$. We denote by ∂_Z the derivative in the direction Z . It acts on $\mathcal{C}^{-\infty}(\mathcal{U})$ and on $\mathcal{C}^{-\infty}(\mathcal{U}, V)$. We extend ∂ to a morphism of algebras from $S(\mathfrak{g})$ to the algebra of differential operators with constant coefficients on \mathfrak{g} . We denote by \mathcal{L}_Z the differential operator defined by:

$$(13) \quad (\mathcal{L}_Z \phi)(X) = \frac{d}{dt} \phi(X - t[Z, X])|_{t=0}.$$

The map $Z \mapsto \mathcal{L}_Z$ is a Lie algebra homomorphism from \mathfrak{g} into the algebra of differential operators on \mathfrak{g} . Let $Z \in \mathfrak{g}$ and $\phi \otimes v \in \mathcal{C}^{-\infty}(\mathcal{U}) \otimes V$, we put:

$$(14) \quad Z.(\phi \otimes v) = \phi \otimes \rho(Z)v + (\mathcal{L}_Z \phi) \otimes v.$$

In other words, if we extend \mathcal{L}_Z (resp. $\rho(Z)$) linearly to a representation of \mathfrak{g} in $\mathcal{C}^{-\infty}(\mathcal{U}, V)$, we have for $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)$:

$$(15) \quad Z.\phi = (\rho(Z) + \mathcal{L}_Z)\phi.$$

We say that $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)$ is locally invariant if for any $Z \in \mathfrak{g}$ we have $Z.\phi = 0$. We put:

$$(16) \quad \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{g}} = \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V) / \forall Z \in \mathfrak{g}, Z.\phi = 0\}.$$

3. SUPPORT $\{0\}$ DISTRIBUTIONS

In this section we assume that \mathfrak{g} is unimodular. We choose an invariant measure dZ on \mathfrak{g} . We define the Dirac function δ_0 on \mathfrak{g} with support $\{0\}$ (which depends on the choice of dZ) by the following. Let $\mathcal{C}_c^\infty(\mathfrak{g})$ be the set of smooth compactly supported functions on \mathfrak{g} . Then:

$$(17) \quad \forall f \in \mathcal{C}_c^\infty(\mathfrak{g}), \int_{\mathfrak{g}} \delta_0(Z) f(Z) dZ = f(0).$$

We have the following well known theorem:

Theorem 3.1. *Let \mathfrak{g} be a finite dimensional unimodular real Lie algebra and V be a finite dimensional \mathfrak{g} -module. Then:*

$$(18) \quad \{\phi \in \mathcal{C}^{-\infty}(\mathfrak{g}, V)^{\mathfrak{g}} / \phi|_{\mathfrak{g} \setminus \{0\}} = 0\} \simeq (V \otimes S(\mathfrak{g}))^{\mathfrak{g}}.$$

The isomorphism (which depends on the choice of dZ) sends $\sum_i v_i \otimes D_i \in (V \otimes S(\mathfrak{g}))^{\mathfrak{g}}$ to $\sum_i (\partial_{D_i} \delta_0) v_i$.

4. SUPPORT IN THE NILPOTENT CONE

From now on, we assume that $\mathfrak{g} = \mathfrak{sl}(2, \mathbb{R})$.

4.1. **Notations.** We put:

$$(19) \quad H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}; \quad X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}; \quad Y = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

We denote by $(h, x, y) \in (\mathfrak{sl}(2, \mathbb{R})^*)^3$ the dual basis of (H, X, Y) . Thus:

$$(20) \quad \begin{pmatrix} h & x \\ y & -h \end{pmatrix} \in \mathfrak{sl}(2, \mathbb{R})^* \otimes \mathfrak{sl}(2, \mathbb{R})$$

is the generic point of $\mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{N} be the nilpotent cone of $\mathfrak{sl}(2, \mathbb{R})$. It is the union of three orbits:

- (i) $\{0\}$.
- (ii) the half cone \mathcal{N}^+ with equations $h^2 + xy = 0$; $x - y > 0$.
- (iii) the half cone \mathcal{N}^- with equations $h^2 + xy = 0$; $x - y < 0$.

We denote by \square the Casimir operator of $\mathfrak{sl}(2, \mathbb{R})$:

$$(21) \quad \square = \frac{1}{2}(\partial_H)^2 + 2\partial_Y\partial_X.$$

It is an invariant differential operator with constant coefficients on $\mathfrak{sl}(2, \mathbb{R})$.

Let $V_1 = \mathbb{R}^2$ be the standard representation of $\mathfrak{sl}(2, \mathbb{R})$. We denote by $(e = (1, 0), f = (0, 1))$ the standard basis of \mathbb{R}^2 . The symplectic form B such that $B(e, f) = 1$ is $\mathfrak{sl}(2, \mathbb{R})$ -invariant. For $v \in V_1$, we define $\mu_1(v) \in \mathfrak{sl}(2, \mathbb{R})$ as the unique element such that:

$$(22) \quad \forall Z \in \mathfrak{sl}(2, \mathbb{R}), \operatorname{tr}(\mu_1(v)Z) = \frac{1}{2}B(v, Zv).$$

It defines a (moment) map:

$$(23) \quad \mu_1 : V_1 \rightarrow \mathfrak{sl}(2, \mathbb{R}).$$

We have $\mu_1(e) = \frac{1}{2}X$ and $\mu_1(f) = -\frac{1}{2}Y$. The function μ_1 is a two-fold covering of \mathcal{N}^+ by $V_1 \setminus \{0\}$.

Let $Z_0 \in \mathcal{N} \setminus \{0\}$. Let \mathcal{U} be a “small” neighborhood of Z_0 . In this section we determine:

$$(24) \quad \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus \mathcal{N}} = 0\}.$$

We can assume that $Z_0 = X \in \mathcal{N}^+$.

4.2. **Restriction to $X + \mathbb{R}Y$.** We define a map:

$$(25) \quad \begin{aligned} \pi : SL(2, \mathbb{R}) \times (X + \mathbb{R}Y) &\rightarrow \mathfrak{sl}(2, \mathbb{R}) \\ (g, Z) &\mapsto \operatorname{Ad}(g)(Z). \end{aligned}$$

This map is submersive. Let I_2 be the identity matrix in $SL(2, \mathbb{R})$. Let $\Delta_X \subset X + \mathbb{R}Y$ be an open interval containing X . We choose a connected open subset $\mathcal{V} \subset SL(2, \mathbb{R})$ such that $I_2 \in \mathcal{V}$. We put:

$$(26) \quad \mathcal{U} = \pi(\mathcal{V} \times \Delta_X).$$

It is an open neighborhood of X in \mathfrak{g} .

Lemma 4.1. *There is an injective (restriction) map:*

$$(27) \quad \mathfrak{I}_X : \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})} \rightarrow \mathcal{C}^{-\infty}(\Delta_X, V)$$

$$\phi \mapsto \phi_X.$$

Proof. The map

$$(28) \quad \pi_{\mathcal{U}} = \pi|_{\mathcal{V} \times \Delta_X} : \mathcal{V} \times \Delta_X \rightarrow \mathcal{U}$$

is a submersion. Thus if $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)$, then $\pi_{\mathcal{U}}^*(\phi)$ is a well defined generalized function on $\mathcal{V} \times \Delta_X$ with values in V . Moreover,

$$(29) \quad \phi = 0 \Leftrightarrow \pi_{\mathcal{U}}^*(\phi) = 0.$$

Now, we assume that ϕ is locally invariant. Then, $\pi_{\mathcal{U}}^*(\phi)$ is also locally invariant and

$$(30) \quad \pi_{\mathcal{U}}^*(\phi) \in \mathcal{C}^{\infty}(\mathcal{V}) \widehat{\otimes} \mathcal{C}^{-\infty}(\Delta_X).$$

(Where $\widehat{\otimes}$ is a completed tensor product.) Thus $\pi_{\mathcal{U}}^*(\phi)$ can be restricted to $\{I_2\} \times \Delta_X \subset \mathcal{V} \times \Delta_X$ (cf. [HC64]). We identify Δ_X and $\{I_2\} \times \Delta_X$. We put:

$$(31) \quad \phi_X \stackrel{\text{def}}{=} \pi_{\mathcal{U}}^*(\phi)|_{\Delta_X}.$$

Since \mathcal{V} is connected and ϕ is locally invariant, we have:

$$(32) \quad \pi_{\mathcal{U}}^*(\phi)(g, Z) = \rho(g)\phi_X(Z).$$

Thus

$$(33) \quad \phi_X = 0 \Leftrightarrow \pi_{\mathcal{U}}^*(\phi) = 0.$$

□

We have for $Z \in \mathfrak{sl}(2, \mathbb{R})$:

$$(34) \quad \mathcal{L}_Z = -h\partial_{[Z, H]} - x\partial_{[Z, X]} - y\partial_{[Z, Y]}.$$

In particular:

$$(35) \quad \mathcal{L}_H = -2x\partial_X + 2y\partial_Y;$$

$$(36) \quad \mathcal{L}_X = 2h\partial_X - y\partial_H;$$

$$(37) \quad \mathcal{L}_Y = x\partial_H - 2h\partial_Y.$$

If \mathcal{V} is sufficiently small, we have $x \neq 0$ on \mathcal{U} . We assume that this condition is realized. It follows that on \mathcal{U} we have:

$$(38) \quad \partial_X = -\frac{1}{2x}\mathcal{L}_H + \frac{y}{x}\partial_Y;$$

$$\partial_H = \frac{1}{x}\mathcal{L}_Y + \frac{2h}{x}\partial_Y.$$

We have $\Delta_X \subset \{X + yY / y \in \mathbb{R}\}$. We use the coordinate $y|_{\Delta_X}$, still denoted by y , on Δ_X . Let $\psi \in \mathcal{C}^{-\infty}(\Delta_X, V_n)$. We put $\psi(y) = \psi(X + yY)$.

Lemma 4.2. *We have:*

$$(39) \quad \mathfrak{I}_X \left(\mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})} \right) = \{ \psi \in \mathcal{C}^{-\infty}(\Delta_X, V) / (\rho(X) + y\rho(Y))\psi(y) = 0 \}.$$

Thus:

$$(40) \quad \mathfrak{I}_X : \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})} \rightarrow \{ \psi \in \mathcal{C}^{-\infty}(\Delta_X, V) / (\rho(X) + y\rho(Y))\psi(y) = 0 \}$$

is an isomorphism

Proof. Since $x|_{\Delta_X} = 1$ and $h|_{\Delta_X} = 0$ we have for $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$:

$$(41) \quad \begin{aligned} (\mathcal{L}_X \phi)_X(y) &= -y(\partial_H \phi)_X(y); \\ \text{and} \quad (\mathcal{L}_Y \phi)_X(y) &= (\partial_H \phi)_X(y). \end{aligned}$$

It follows that we have:

$$(42) \quad (\mathcal{L}_X \phi)_X(y) + y(\mathcal{L}_Y \phi)_X(y) = 0.$$

Let $\psi \in \mathfrak{I}_X \left(\mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})} \right)$. Then, there is $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$ such that $\psi = \phi_X$. We have:

$$(43) \quad \begin{aligned} (\rho(X) + y\rho(Y))\psi(y) &= (\rho(X) + y\rho(Y))\phi_X(y) \\ &= (\rho(X)\phi)_X(y) + y(\rho(Y)\phi)_X(y) + (\mathcal{L}_X \phi)_X(y) + y(\mathcal{L}_Y \phi)_X(y) \\ &= \left((\rho(X) + \mathcal{L}_X)\phi \right)_X(y) + y \left((\rho(Y) + \mathcal{L}_Y)\phi \right)_X(y) = 0. \end{aligned}$$

Let $\psi \in \mathcal{C}^{-\infty}(\Delta_X, V)$ such that $(\rho(X) + y\rho(Y))\psi(y) = 0$. We define $\tilde{\psi} \in \mathcal{C}^{-\infty}(\mathcal{V} \times \Delta_X)$ by the formula:

$$(44) \quad \tilde{\psi}(g, y) = \rho(g)\psi(y).$$

Since ρ is a smooth function on $SL(2, \mathbb{R})$ with values in $GL(V)$, this is a well defined generalized function on $\mathcal{V} \times \Delta_X$ with values in V .

Let $(g, Z) \in \mathcal{V} \times \Delta_X$. Let $(g', Z') \in \mathcal{V} \times \Delta_X$ such that $\text{Ad}(g)(Z) = \text{Ad}(g')(Z')$. Then, $\text{Ad}((g')^{-1}g)Z = Z'$. We put $G^Z = \{g'' \in SL(2, \mathbb{R}) / \text{Ad}(g'')(Z) = Z\}$. For $g'' \in SL(2, \mathbb{R})$, we have $\text{Ad}(g'')(Z) \in \Delta_X \Leftrightarrow g'' \in G^Z$. Then, the fiber of $\pi_{\mathcal{U}}$ at (g, Z) is included in $\{(g', Z) / g^{-1}g' \in G^Z\}$. Moreover, for $Z' \in \mathfrak{sl}(2, \mathbb{R})$, $[Z, Z'] = 0 \Leftrightarrow Z' \in \mathbb{R}Z$. Thus, since \mathcal{V} is connected, the condition $(\rho(X) + y\rho(Y))\psi(y) = 0$ on Δ_X ensures that $\tilde{\psi}$ is constant along the fibers of $\pi_{\mathcal{U}}$. Thus there is a well defined generalized function $\overline{\psi}$ on \mathcal{U} such that:

$$(45) \quad \pi_{\mathcal{U}}^*(\overline{\psi}) = \tilde{\psi}.$$

It follows from the construction that $(\overline{\psi})_X = \psi$.

□

The hypothesis $\phi|_{\mathcal{U} \setminus \mathcal{N}} = 0$ means that ϕ_X is supported in $\{X\} \subset \Delta_X$.

4.3. **Radial part of \square .** In the neighborhood \mathcal{U} of X defined in section 4.2:

$$(46) \quad \begin{aligned} \square &= \frac{1}{2}(\partial_H)^2 + 2\partial_Y\partial_X \\ &= \frac{1}{2}\left(\frac{1}{x}\mathcal{L}_Y + \frac{2h}{x}\partial_Y\right)^2 + 2\partial_Y\left(\frac{-1}{2x}\mathcal{L}_H + \frac{y}{x}\partial_Y\right). \end{aligned}$$

We define the radial part of \square as the differential operator \square_X on $\mathcal{C}^{-\infty}(\Delta_X, V)$:

$$(47) \quad \square_X = \left(3 + \rho(H) + 2y\frac{\partial}{\partial y}\right)\frac{\partial}{\partial y} + \frac{1}{2}\rho(Y)^2.$$

This definition is justified by the following lemma:

Lemma 4.3. *Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$, then we have:*

$$(48) \quad (\square\phi)_X = \square_X\phi_X.$$

Proof. Since $x|_{\Delta_X} = 1$ and $h|_{\Delta_X} = 0$, we have:

$$(49) \quad \begin{aligned} (\square\phi)_X &= \frac{1}{2}\left((\mathcal{L}_Y^2 + 2\mathcal{L}_Y\frac{h}{x}\frac{\partial}{\partial y})\phi\right)_X + 2\left(\frac{-1}{2}\left(\frac{\partial}{\partial y}\mathcal{L}_H\phi\right)_X + \left(\frac{\partial}{\partial y}y\frac{\partial}{\partial y}\phi\right)_X\right) \\ &= \frac{1}{2}\left((\rho(Y)^2 + 2(x\partial_H - 2h\partial_Y)\frac{h}{x}\frac{\partial}{\partial y})\phi\right)_X \\ &\quad + 2\left(\frac{-1}{2}\left(-\rho(H)\frac{\partial}{\partial y}\phi_X\right) + \frac{\partial}{\partial y}\phi_X + y\left(\frac{\partial}{\partial y}\right)^2\phi_X\right) \\ &= \frac{1}{2}\left(\rho(Y)^2 + 2\frac{\partial}{\partial y}\right)\phi_X + \left(\rho(H) + 2 + 2y\frac{\partial}{\partial y}\right)\frac{\partial}{\partial y}\phi_X \\ &= \left(3 + \rho(H) + 2y\frac{\partial}{\partial y}\right)\frac{\partial}{\partial y}\phi_X + \frac{1}{2}\rho(Y)^2\phi_X = \square_X\phi_X. \end{aligned}$$

□

4.4. **The Dirac function $\delta_{\mathcal{N}^+}$ (resp. $\delta_{\mathcal{N}^-}$).** Let $dZ = dx dy dh$ be the Lebesgue measure on $\mathfrak{sl}(2, \mathbb{R})$. Let $(e^*, f^*) \in (V_1^*)^2$ be the dual basis of (e, f) . The Lebesgue measure $dv = -2de^*df^*$ on V_1 is $\mathfrak{sl}(2, \mathbb{R})$ -invariant. We define an invariant generalized function $\delta_{\mathcal{N}^+}$ (resp. $\delta_{\mathcal{N}^-}$) on $\mathfrak{sl}(2, \mathbb{R})$ and supported in $\mathcal{N}^+ \cup \{0\}$ (resp. $\mathcal{N}^- \cup \{0\}$) by:

$$(50) \quad \begin{aligned} \forall g \in \mathcal{C}_c^\infty(\mathfrak{sl}(2, \mathbb{R})), \quad &\int_{\mathfrak{sl}(2, \mathbb{R})} \delta_{\mathcal{N}^+}(Z)g(Z)dZ \stackrel{\text{def}}{=} \int_{V_1} g \circ \mu_1(v)dv \\ \left(\text{resp. } \forall g \in \mathcal{C}_c^\infty(\mathfrak{sl}(2, \mathbb{R})), \quad &\int_{\mathfrak{sl}(2, \mathbb{R})} \delta_{\mathcal{N}^-}(Z)g(Z)dZ \stackrel{\text{def}}{=} \int_{V_1} g \circ (-\mu_1)(v)dv\right). \end{aligned}$$

We put:

$$(51) \quad \delta_X = (\delta_{\mathcal{N}^+})_X \in \mathcal{C}^{-\infty}(\Delta_X).$$

We still denote by dy the Lebesgue measure on Δ_X . It is invariant. Let $g \in \mathcal{C}_c^\infty(\Delta_X)$. Then we have:

$$(52) \quad \int_{\Delta_X} \delta_X(y)g(y)dy = g(0).$$

4.5. Irreducible representations. If $V = V^1 \oplus \cdots \oplus V^n$ where V^i is an irreducible representation of $\mathfrak{sl}(2, \mathbb{R})$, then we have:

$$(53) \quad \mathcal{C}^{-\infty}(\mathcal{U}, V) = \bigoplus_{i=1}^n \mathcal{C}^{-\infty}(\mathcal{U}, V^i),$$

every subspace being stable for $\mathfrak{sl}(2, \mathbb{R})$. Thus we can assume from now on that the representation of $\mathfrak{sl}(2, \mathbb{R})$ in V is irreducible.

We fix the Cartan subalgebra $\mathfrak{h} = \mathbb{R}H$ and the positive root $2h$ (we still denote by h its restriction to \mathfrak{h}). Let $n \in \mathbb{N}$. We denote by V_n the irreducible representation of $\mathfrak{sl}(2, \mathbb{R})$ with highest weight nh . We have $\dim(V_n) = n + 1$. We decompose V_n under the action of $\mathbb{R}H$. We fix $v_0 \in V_n \setminus \{0\}$ a vector of weight $-nh$:

$$(54) \quad \rho(H)v_0 = -nv_0.$$

We put for $0 \leq i \leq n$: $v_i = \rho(X)^i v_0$. We have $\rho(X)v_n = 0$ and $\rho(H)v_i = (-n + 2i)v_i$. On the other hand, $\rho(Y)v_0 = 0$ and for $1 \leq i \leq n$: $\rho(Y)v_i = (n - i + 1)v_{i-1}$.

4.6. A basic function on \mathcal{N}^+ . We construct a function $s_n : \mathcal{U} \cap \mathcal{N}^+ \rightarrow V_n$ which is the basic tool to generate all the generalized functions we are looking for.

4.6.1. Case n even. In this case V_n is isomorphic to the irreducible component of $S^{\frac{n}{2}}(\mathfrak{sl}(2, \mathbb{R}))$ (under adjoint action of $\mathfrak{sl}(2, \mathbb{R})$) generated by $X^{\frac{n}{2}}$. From now on we will identify V_n with this component. We denote by $s_n : \mathcal{N} \rightarrow V_n$ the invariant map defined by:

$$(55) \quad s_n(Z) = Z^{\frac{n}{2}}.$$

4.6.2. Case $n = 1$. We recall that $\mu_1 : V_1 \setminus \{0\} \rightarrow \mathcal{N}^+$ is a two-fold covering with $\mu_1(e) = \frac{1}{2}X$. If \mathcal{U} is a sufficiently small connected neighborhood of X , there exists a unique continuous section s_1 of μ_1 in $\mathcal{U} \cap \mathcal{N}^+$ such that $s_1(\frac{1}{2}X) = e$. We have $s_1 : \mathcal{U} \cap \mathcal{N}^+ \rightarrow V_1$. It satisfies:

$$(56) \quad \forall Z \in \mathcal{U} \cap \mathcal{N}^+, \mu_1(s_1(Z)) = Z.$$

4.6.3. Case n odd. More generally, when n is odd, V_n is isomorphic to the irreducible component of $V_1 \otimes S^{\frac{n-1}{2}}(\mathfrak{sl}(2, \mathbb{R}))$ generated by $e \otimes X^{\frac{n-1}{2}}$. From now on we will identify V_n with this component. Let \mathcal{U} be the above neighborhood of X . We define a function $s_n : \mathcal{U} \cap \mathcal{N}^+ \rightarrow V_n$ by:

$$(57) \quad \forall Z \in \mathcal{U} \cap \mathcal{N}^+, s_n(Z) = s_1(Z) \otimes Z^{\frac{n-1}{2}} \in V_n.$$

4.7. Basic theorem. Let \mathcal{U} be an open subset of $\mathfrak{sl}(2, \mathbb{R})$. We put:

$$(58) \quad \mathcal{S}_n(\mathcal{U}) = \left\{ \phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus \mathcal{N}} = 0 \right\}.$$

Theorem 4.1. *Let $n \in \mathbb{N}$. Let \mathcal{U} be an open connected neighborhood of X such that the function s_n is well defined on $\mathcal{U} \cap \mathcal{N}$ (cf. section 4.6) and \mathfrak{I}_X is bijective (cf. section 4.2). Then:*

(i) *When n is even, $\mathcal{S}_n(\mathcal{U})$ is an infinite dimensional vector space with basis:*

$$(59) \quad \left(\square^k(s_n \delta_{\mathcal{N}^+}) \right)_{k \in \mathbb{N}}.$$

(ii) *When n is odd, $\dim(\mathcal{S}_n(\mathcal{U})) = \frac{n+1}{2}$ and a basis is given by:*

$$(60) \quad \left(\square^k(s_n \delta_{\mathcal{N}^+}) \right)_{0 \leq k \leq \frac{n-1}{2}}.$$

Remark: Since $\delta_{\mathcal{N}^+}(Z)dZ$ is a measure on $\mathfrak{sl}(2, \mathbb{R})$ with support $\mathcal{N}^+ \cup \{0\}$ and s_n is a smooth function on $\mathcal{U} \cap \mathcal{N}$ with values in V_n , $s_n \delta_{\mathcal{N}^+}$ is a well defined generalized function on \mathcal{U} with values in V_n .

Proof. Thanks to the isomorphism \mathfrak{I}_X we have to determine the space:

$$(61) \quad \{\psi \in \mathcal{C}^{-\infty}(\Delta_X, V_n) / \psi|_{\Delta_X \setminus \{0\}} = 0 \text{ and } (\rho(X) + y\rho(Y))\psi(y) = 0\}.$$

Let $\psi \in \mathcal{C}^{-\infty}(\Delta_X, V_n)$. We write:

$$(62) \quad \psi(y) = \sum_{i=0}^n \psi_i(y) v_i,$$

where $\psi_i \in \mathcal{C}^{-\infty}(\Delta_X)$ and $(v_i)_{0 \leq i \leq n}$ is the basis defined in section 4.5. We put:

$$(63) \quad \delta^k(y) = \left(\frac{\partial}{\partial y}\right)^k \delta_X(y).$$

Since ψ is supported in \mathcal{N} and $\Delta_X \cap \mathcal{N} = \{X\}$, there exists $a_{i,k} \in \mathbb{R}$, all equal to zero but for finite number, such that:

$$(64) \quad \psi_i(y) = \sum_{k \in \mathbb{N}} a_{i,k} \delta^k(y).$$

For $n = 0$, we have $\rho = 0$ and the condition $(\rho(X) + y\rho(Y))\psi(y) = 0$ is automatically satisfied.

For $n \geq 1$, we put $\alpha_i = (n - i + 1)i$. We have $y\delta^0(y) = 0$ and for $k \geq 1$, $y\delta^k(y) = -k\delta^{k-1}(y)$. Thus:

$$(65) \quad \sum_{0 \leq i \leq n-1, k \in \mathbb{N}} a_{i,k} \delta^k(y) v_{i+1} - \sum_{1 \leq i \leq n, k \geq 1} \alpha_i a_{i,k} k \delta^{k-1}(y) v_{i-1} = 0.$$

It follows:

$$(66) \quad \begin{cases} a_{n-1,k} = 0 & \text{for } k \geq 0; \\ a_{1,k} = 0 & \text{for } k \geq 1; \\ a_{i-1,k} = (k+1)(i+1)(n-i)a_{i+1,k+1} & \text{for } n \geq 2, 1 \leq i \leq n-1 \text{ and } k \geq 0. \end{cases}$$

It follows in particular

- (i) from the first and the last relations that $\forall i, k \geq 0$ with $2i+1 \leq n$: $a_{n-(2i+1),k} = 0$;
- (ii) from the last relation that $\forall i \geq 0$ with $2i \leq n$, $(a_{n-2i,k})_{k \geq 0}$ is completely determined by $(a_{n,k})_{k \geq 0}$.

We distinguish between the two cases according to the parity of n .

n even: In this case, for $n \geq 2$, the second relation follows from (i). Hence the map:

$$(67) \quad \{\psi \in \mathcal{C}^{-\infty}(\Delta_X, V_n) / \psi|_{\Delta_X \setminus \{0\}} = 0 \text{ and } (\rho(X) + y\rho(Y))\psi(y) = 0\} \rightarrow \mathbb{R}^{\mathbb{N}}$$

$$\psi(y) = \sum_{0 \leq i \leq n, k \in \mathbb{N}} a_{i,k} \delta^k(y) v_i \mapsto (a_{n,k})_{k \in \mathbb{N}}$$

is bijective. This is also true for $n = 0$.

n odd: It follows from the two last relations that for $k \geq i \geq 1$ $a_{2i-1,k} = 0$. In particular, the map:

$$(68) \quad \{\psi \in \mathcal{C}^{-\infty}(\Delta_X, V_n) / \psi|_{\Delta_X \setminus \{0\}} = 0 \text{ and } (\rho(X) + y\rho(Y))\psi(y) = 0\} \rightarrow \mathbb{R}^{\frac{n+1}{2}}$$

$$\psi(y) = \sum_{0 \leq i \leq n, k \in \mathbb{N}} a_{i,k} \delta^k(y) v_i \mapsto (a_{n,0}, \dots, a_{n,\frac{n-1}{2}})$$

is bijective.

This proves the first part of the theorem on the dimension of $\mathcal{S}_n(\mathcal{U})$. It remains to prove that the functions $\square^k(s_n \delta_{\mathcal{N}})$ form a basis of $\mathcal{S}_n(\mathcal{U})$. We have for $\psi(y) = \sum_{i=0}^n \sum_{k \in \mathbb{N}} a_{i,k} \delta^k(y) v_i \in \mathcal{C}^{-\infty}(\Delta_X, V_n)$ such that $\rho(X + yY)\psi(y) = 0$:

$$(69) \quad \square_X \psi(y) = (3 + \rho(H) + 2y\partial_Y) \sum_{k \in \mathbb{N}} a_{n,k} \delta^{k+1}(y) v_n + \sum_{i=0}^{n-1} \dots v_i$$

$$= \sum_{k \in \mathbb{N}} (n - 2k - 1) a_{n,k} \delta^{k+1}(y) v_n + \sum_{i=0}^{n-1} \dots v_i$$

where \dots are elements of $\mathcal{C}^{-\infty}(\Delta_X)$.

n even: Since $v_n = X^{\frac{n}{2}}$, we have $(s_n \delta_{\mathcal{N}})_X(y) = \delta_X(y) X^{\frac{n}{2}}$. By induction on k , it follows:

$$(70) \quad (\square^k(s_n \delta_{\mathcal{N}}))_X(y) = (n - 2k + 1) \dots (n - 1) \delta^k(y) X^{\frac{n}{2}}$$

$$+ \text{ terms with } X^{\frac{n}{2}-i} \text{ for } i \geq 1.$$

Since n is even $n - 2k + 1 \neq 0$. The result follows.

n odd: Since $v_n = e \otimes X^{\frac{n-1}{2}}$, we have $(s_n \delta_{\mathcal{N}})_X(y) = \delta_X(y)(e \otimes X^{\frac{n-1}{2}})$. By induction on k , it follows:

$$(71) \quad (\square^k(s_n \delta_{\mathcal{N}}))_X(y) = (n - 2k + 1) \dots (n - 1) \delta^k(y)(e \otimes X^{\frac{n-1}{2}})$$

$$+ \text{ terms with } e \otimes X^{\frac{n-1}{2}-i} \text{ for } i \geq 1.$$

In this case for $k = \frac{n+1}{2}$, $n - 2k + 1 = 0$. Thus, since $\square^k(s_n \delta_{\mathcal{N}})$ is invariant, it follows from the isomorphism (68) that for $k \geq \frac{n+1}{2}$: $\square^k(s_n \delta_{\mathcal{N}}) = 0$. The result follows. \square

4.8. Global version. Let \mathcal{U} be an open subset of $\mathfrak{sl}(2, \mathbb{R})$. We put:

$$(72) \quad \mathcal{S}_n^0(\mathcal{U}) = \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus \{0\}} = 0\};$$

$$(73) \quad \mathcal{S}_n^{\pm}(\mathcal{U}) = \{\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V_n)^{\mathfrak{sl}(2, \mathbb{R})} / \phi|_{\mathcal{U} \setminus (\mathcal{N}^{\pm} \cup \{0\})} = 0\}.$$

Theorem 4.2. *Let \mathcal{U} be an $SL(2, \mathbb{R})$ -invariant open subset of $\mathfrak{sl}(2, \mathbb{R})$. Then we have:*

(i)

$$(74) \quad \begin{cases} \mathcal{S}_n^0(\mathcal{U}) = \{0\} & \text{if } 0 \notin \mathcal{U}; \\ \mathcal{S}_n^0(\mathcal{U}) \simeq (V_n \otimes S(\mathfrak{sl}(2, \mathbb{R})))^{\mathfrak{sl}(2, \mathbb{R})} & \text{if } 0 \in \mathcal{U}. \end{cases}$$

(ii) When n is even, we have:

$$(75) \quad \mathcal{S}_n(\mathcal{U}) = \mathcal{S}_n^0(\mathcal{U}) \oplus \text{Vect}\{\square^k(s_n\delta_{\mathcal{N}^+})|_{\mathcal{U}/k} \in \mathbb{N}\} \oplus \text{Vect}\{\square^k(s_n\delta_{\mathcal{N}^-})|_{\mathcal{U}/k} \in \mathbb{N}\}$$

$$(76) \quad \mathcal{S}_n^\pm(\mathcal{U}) = \mathcal{S}_n^0(\mathcal{U}) \oplus \text{Vect}\{\square^k(s_n\delta_{\mathcal{N}^\pm})|_{\mathcal{U}/k} \in \mathbb{N}\}$$

(iii) When n is odd:

$$(77) \quad \mathcal{S}_n(\mathcal{U}) = \mathcal{S}_n^\pm(\mathcal{U}) = \mathcal{S}_n^0(\mathcal{U})$$

Proof. (i) It follows from Theorem 3.1.

(ii) When n is even, the function $\delta_{\mathcal{N}}^\pm$ is defined on $\mathfrak{sl}(2, \mathbb{R})$, the function s_n is defined on \mathcal{N} and the product $s_n\delta_{\mathcal{N}^\pm}$ is well defined (cf. Remark of Theorem 4.1). Then the result follows from Theorem 4.1.

(iii) Let n be odd. We assume that $\mathcal{U} \cap \mathcal{N} \neq \emptyset$. Since \mathcal{U} is $SL(2, \mathbb{R})$ -invariant, we have $\mathcal{N}^+ \subset \mathcal{U}$ or $\mathcal{N}^- \subset \mathcal{U}$. We assume that $\mathcal{N}^+ \subset \mathcal{U}$ (the case $\mathcal{U} \subset \mathcal{N}^-$ is similar).

Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$. Let $\mathcal{U}_0 \subset \mathcal{U}$ be a suitable neighborhood of X where s_1 (and thus s_n) is defined (cf. section 4.6). There exists $(a_0, \dots, a_{\frac{n-1}{2}}) \in \mathbb{R}^{\frac{n+1}{2}}$ such that on \mathcal{U}_0 (cf. Theorem 4.1):

$$(78) \quad \phi(Z) = \sum_{k=0}^{\frac{n+1}{2}} a_k \square^k(s_n(Z)\delta_{\mathcal{N}^+}(Z)) = \sum_{k=0}^{\frac{n+1}{2}} a_k \square^k((s_1(Z) \otimes Z^{\frac{n-1}{2}})\delta_{\mathcal{N}^+}(Z)).$$

Since $\mu_1 : V_1 \setminus \{0\} \rightarrow \mathcal{N}^+$ is a non trivial two-fold covering, there is not any continuous section. In other words there is not any continuous $SL(2, \mathbb{R})$ -invariant map $s : \mathcal{N}^+ \rightarrow V_1$ such that for any $Z \in \mathcal{U}_0$, $s(Z) = s_1(Z)$. Thus $a_0 = \dots = a_{\frac{n-1}{2}} = 0$. The result follows. \square

5. INVARIANT SOLUTIONS OF DIFFERENTIAL EQUATIONS

5.1. Introduction. Let $\mathcal{C}_V = (\text{End}(V) \otimes S(\mathfrak{sl}(2, \mathbb{R})))^{\mathfrak{sl}(2, \mathbb{R})}$ be the algebra of $\text{End}(V)$ -valued invariant differential operators with constant coefficients on \mathfrak{g} . It is the *classical family algebra* in the terminology of Kirillov (cf. [Kir00]). When $V = V_n$ is the $(n+1)$ -dimensional irreducible representation of $\mathfrak{sl}(2, \mathbb{R})$, we put $\mathcal{C}_n = \mathcal{C}_{V_n}$.

Let $\mathcal{U} \subset \mathfrak{sl}(2, \mathbb{R})$ be an open subset. It is a natural and interesting problem to determine the generalized functions $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$ such that $\mathcal{C}_V\phi$ is finite dimensional.

We recall that $S(\mathfrak{sl}(2, \mathbb{R}))^{\mathfrak{sl}(2, \mathbb{R})} = \mathbb{R}[\square]$. It is a subalgebra of \mathcal{C}_V . An other subalgebra of \mathcal{C}_V is $\text{End}(V)^{\mathfrak{sl}(2, \mathbb{R})}$. When $V = V_n$, we put:

$$(79) \quad M_n = \rho_n(X)Y + \rho_n(Y)X + \frac{1}{2}\rho_n(H)H \in \mathcal{C}_n$$

According N. Rozhkovskaya (cf. [Roz03]), \mathcal{C}_n is a free $S(\mathfrak{sl}(2, \mathbb{R}))^{\mathfrak{sl}(2, \mathbb{R})}$ -module with basis $\mathcal{B}_n = (1, M_n, \dots, (M_n)^n)$.

Lemma 5.1. *Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$. Then we have:*

$$(80) \quad \dim_{\mathbb{R}}(\mathcal{C}_V\phi) < \infty \Leftrightarrow \dim_{\mathbb{R}}(\mathbb{R}[\square]\phi) < \infty$$

Proof. We argue as in [Roz03]. Let H be the set of harmonic polynomials in $S(\mathfrak{sl}(2, \mathbb{R}))$. Then, $S(\mathfrak{sl}(2, \mathbb{R})) = \mathbb{R}[\square] \otimes H$ (cf. [Kos63]), and:

$$(81) \quad \mathcal{C}_V = \mathbb{R}[\square] \otimes (H \otimes \text{End}(V))^{\mathfrak{sl}(2, \mathbb{R})}.$$

Since $\dim_{\mathbb{R}}(H \otimes \text{End}(V))^{\mathfrak{sl}(2, \mathbb{R})} < \infty$, the result follows.

□

Remark: Since $\mathbb{R}[\square] \subset \mathbb{R}[\square] \otimes \text{End}(V)^{\mathfrak{sl}(2, \mathbb{R})} \subset \mathcal{C}_V$, the condition $\dim(\mathcal{C}_V \phi) < \infty$ is also equivalent to the existence of $r \in \mathbb{N}$ and $(A_0, \dots, A_{r-1}) \in (\text{End}(V)^{\mathfrak{sl}(2, \mathbb{R})})^r$ such that:

$$(82) \quad (\square^r + A_{r-1}\square^{r-1} + \dots A_1\square + A_0)\phi = 0.$$

Useful examples of (82) are $(\square - \lambda)^k \phi = 0$ for $\lambda \in \mathbb{C}$ and generalized functions with values in a complex representation. We give such an example below.

Definition 5.1. Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$. We say that ϕ is \square -finite if $\dim_{\mathbb{R}}(\mathbb{R}[\square]\phi) < \infty$.

In other words, ϕ is \square -finite if there exists $r \in \mathbb{N}$ and $(a_0, \dots, a_{r-1}) \in \mathbb{R}^r$ such that

$$(83) \quad (\square^r + a_{r-1}\square^{r-1} + \dots a_1\square + a_0)\phi = 0.$$

Example: (This was our original motivation to study this problem.) Let $\mathfrak{g} = \mathfrak{g}_0 \oplus \mathfrak{g}_1$ be a Lie superalgebra. We define the generalized functions on \mathfrak{g} as the generalized functions on \mathfrak{g}_0 with values in the exterior algebra $\Lambda(\mathfrak{g}_1^*)$ of \mathfrak{g}_1^* :

$$(84) \quad \mathcal{C}^{-\infty}(\mathfrak{g}) \stackrel{\text{def}}{=} \mathcal{C}^{-\infty}(\mathfrak{g}_0) \otimes \Lambda(\mathfrak{g}_1^*) = \mathcal{C}^{-\infty}(\mathfrak{g}_0, \Lambda(\mathfrak{g}_1^*)).$$

We assume that \mathfrak{g} has a non degenerate invariant symmetric even bilinear form B . Let $\Omega \in S^2(\mathfrak{g})$ be the Casimir operator associated with B . We have $\Omega = \Omega_0 + \Omega_1$ with $\Omega_0 \in S^2(\mathfrak{g}_0)$ and $\Omega_1 \in \Lambda^2(\mathfrak{g}_1)$. We consider Ω_1 as an element of $\text{End}(\Lambda(\mathfrak{g}_1^*))$ acting by interior product. When they can be evaluated (cf. for example [Lav98, Chapitre III.5]), the Fourier transforms of the coadjoint orbits in \mathfrak{g}^* are invariant generalized functions ϕ on \mathfrak{g} subject to equations of the form $(\Omega - \lambda)\phi = 0$ with $\lambda \in \mathbb{C}$. It can be written $(\Omega_0 + (\Omega_1 - \lambda))\phi = 0$ (for $\mathfrak{g}_0 = \mathfrak{sl}(2, \mathbb{R})$ it is of the form (82) with $\Omega_0 = \square$ and $A_0 = \Omega_1 - \lambda$). We have:

$$(85) \quad (\Omega_0 - \lambda)^k = \sum_{i=0}^k \binom{k}{i} (\Omega - \lambda)^i (-\Omega_1)^{k-i}.$$

For $k > \frac{\dim(\mathfrak{g}_1)}{2}$, we have $\Omega_1^k = 0$. It follows that for $k > 1 + \frac{\dim(\mathfrak{g}_1)}{2}$ we have:

$$(86) \quad (\Omega_0 - \lambda)^k \phi = 0.$$

this equation is of the form of (82).

5.2. Generalized functions with support $\{0\}$. We immediately obtain from Theorem 3.1

Theorem 5.1. Let V be a representation of $\mathfrak{sl}(2, \mathbb{R})$. Let $\phi \in \mathcal{C}^{-\infty}(\mathfrak{sl}(2, \mathbb{R}), V)^{\mathfrak{sl}(2, \mathbb{R})}$ such that $\phi|_{\mathfrak{sl}(2, \mathbb{R}) \setminus \{0\}} = 0$ and ϕ is \square -finite. Then, we have $\phi = 0$.

5.3. Support in the nilpotent cone: local version.

Theorem 5.2. *Let $n \in \mathbb{N}$. Let V_n be the irreducible $n+1$ -dimensional representation of $\mathfrak{sl}(2, \mathbb{R})$. Let W be a finite dimensional vector space with trivial action of $\mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{U} be an open connected neighborhood of X such that the function s_n is well defined on $\mathcal{U} \cap \mathcal{N}$ (cf. section 4.6) and \mathfrak{I}_X is bijective (cf. section 4.2). Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, W \otimes V_n)^{\mathfrak{sl}(2, \mathbb{R})}$ such that $\phi|_{\mathcal{U} \setminus \mathcal{N}} = 0$. Let $r \in \mathbb{N}$ and $(a_0, \dots, a_{r-1}) \in \mathbb{R}^r$ such that: $\left(\square^r + \sum_{k=0}^{r-1} a_k \square^k\right)\phi = 0$.*

Then, we have $\phi = 0$ when at least one of the following conditions is satisfied:

- (i) n is even;
- (ii) n is odd and $a_0 \neq 0$.

Proof. Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, W \otimes V_n)^{\mathfrak{sl}(2, \mathbb{R})}$ such that $\phi|_{\mathcal{U} \setminus \mathcal{N}} = 0$. From Theorem 4.1 we obtain that there exist $p \in \mathbb{N}$, with $p = \frac{n-1}{2}$ if n is odd and $(w_0, \dots, w_p) \in W^{p+1}$, such that:

$$(87) \quad \phi = \sum_{i=0}^p w_i \otimes \square^i(s_n \delta_{\mathcal{N}^+}).$$

Then:

- (i) When n is even, for $0 \leq j \leq p+r$, we have $\sum_{k+i=j} a_k w_i = 0$.
- (ii) When n is odd, for $0 \leq j \leq \frac{n-1}{2}$, we have $\sum_{k+i=j} a_k w_i = 0$.

The result follows. □

Remark: When n is odd, in contrast with the classical case ($V = V_0$ is the trivial representation) there exist (in a neighborhood of X) non trivial locally invariant solutions of the equation $\square^k \phi = 0$ supported in the nilpotent cone! For example, if $k \geq \frac{n+1}{2}$ the functions $\phi = \square^i(s_n \delta_{\mathcal{N}^+})$ for $0 \leq i \leq \frac{n-1}{2}$ are not trivial, supported in the nilpotent cone and satisfy the equation $\square^k \phi = 0$.

When we consider the equation $(\square - \lambda)^k \phi = 0$ for $\lambda \in \mathbb{C} \setminus \{0\}$, then the trivial solution is again the only one supported in the nilpotent cone.

5.4. Support in the nilpotent cone: global version.

Theorem 5.3. *Let V be a real finite dimensional representation of $\mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{U} be an $SL(2, \mathbb{R})$ -invariant open subset of $\mathfrak{sl}(2, \mathbb{R})$. Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$ such that $\phi|_{\mathcal{U} \setminus \mathcal{N}} = 0$ and ϕ is \square -finite. Then we have $\phi = 0$.*

Proof. It is enough to prove the theorem for V irreducible. Then, the result follows from Theorem 4.2, Theorem 5.2 and Theorem 5.1. □

6. GENERAL INVARIANT GENERALIZED FUNCTIONS

6.1. Main theorem.

Theorem 6.1. *Let V be a real finite dimensional representation of $\mathfrak{sl}(2, \mathbb{R})$. Let \mathcal{U} be an $SL(2, \mathbb{R})$ -invariant open subset of $\mathfrak{sl}(2, \mathbb{R})$. Let $\phi \in \mathcal{C}^{-\infty}(\mathcal{U}, V)^{\mathfrak{sl}(2, \mathbb{R})}$ such that ϕ is \square -finite. Then ϕ is determined by $\phi|_{\mathcal{U} \setminus \mathcal{N}}$ and $\phi|_{\mathcal{U} \setminus \mathcal{N}}$ is an analytic function.*

Proof. The fact that ϕ is determined by $\phi|_{\mathcal{U} \setminus \mathcal{N}}$ follows from Theorem 5.3. The fact that $\phi|_{\mathcal{U} \setminus \mathcal{N}}$ is analytic can be proved exactly as in [HC65]. \square

Remark: In general ϕ will not be locally L^1 . Indeed, let $\phi_0 \in \mathcal{C}^{-\infty}(\mathfrak{sl}(2, \mathbb{R}))^{\mathfrak{sl}(2, \mathbb{R})}$ a non zero \square -finite generalized function. Then ϕ_0 is locally L^1 , but for $k \in \mathbb{N}^*$:

$$(88) \quad M_n^k \phi_0 \in \mathcal{C}^{-\infty}(\mathfrak{sl}(2, \mathbb{R}), \text{End}(V_n))^{\mathfrak{sl}(2, \mathbb{R})}$$

is usually not locally L^1 .

6.2. Application to the Superpfaffian. Let us consider the Lie superalgebra $\mathfrak{g} = \mathfrak{spo}(2, 2n)$. Its even part is $\mathfrak{g}_0 = \mathfrak{sl}(2, \mathbb{R}) \oplus \mathfrak{so}(2n, \mathbb{R})$. Its odd part is $\mathfrak{g}_1 = V_1 \otimes W$ where W is the standard $2n$ -dimensional representation of $\mathfrak{so}(2n, \mathbb{R})$.

In [Lav04] we constructed a particular invariant generalized function Spf on $\mathfrak{spo}(2, 2n)$ called Superpfaffian. It generalizes the Pfaffian on $\mathfrak{so}(2n, \mathbb{R})$ and the inverse square root of the determinant on $\mathfrak{sl}(2, \mathbb{R})$. As it is a polynomial of degree n on $\mathfrak{so}(2n, \mathbb{R})$, we may consider that we have:

$$(89) \quad \text{Spf} \in \mathcal{C}^{-\infty}\left(\mathfrak{sl}(2, \mathbb{R}), \bigoplus_{k=0}^n S^k(\mathfrak{so}(2n, \mathbb{R})^*) \otimes \Lambda(\mathfrak{g}_1^*)\right)^{\mathfrak{sl}(2, \mathbb{R})}.$$

Let Ω (resp. \square , Ω'_0 , Ω_1) be the Casimir operator on $\mathfrak{spo}(2, 2n)$ (resp. on $\mathfrak{sl}(2, \mathbb{R})$, $\mathfrak{so}(2n, \mathbb{R})$, \mathfrak{g}_1). Then $\Omega = \square + \Omega'_0 + \Omega_1$ and

$$(90) \quad \Omega'_0 + \Omega_1 \in \text{End}\left(\bigoplus_{k=0}^n S^k(\mathfrak{so}(2n, \mathbb{R})^*) \otimes \Lambda(\mathfrak{g}_1^*)\right)^{\mathfrak{sl}(2, \mathbb{R})}$$

is a nilpotent endomorphism. The superpfaffian satisfies:

$$(91) \quad (\square + (\Omega'_0 + \Omega_1)) \text{Spf} = \Omega \text{Spf} = 0.$$

The function Spf is analytic on $\mathfrak{sl}(2, \mathbb{R}) \setminus \mathcal{N}$ and in [Lav04] an explicit formula is given for $\text{Spf}(X) \in \bigoplus_{k=0}^n S^k(\mathfrak{so}(2n, \mathbb{R})^*) \otimes \Lambda(\mathfrak{g}_1^*)$ with $X \in \mathfrak{sl}(2, \mathbb{R}) \setminus \mathcal{N}$. However, since Spf is not locally L^1 (cf. [Lav04]), it is not clear whether Spf is determined by its restriction to $\mathfrak{sl}(2, \mathbb{R}) \setminus \mathcal{N}$ or not. In [Lav04] we proved that Spf is characterized, as an invariant generalized function on $\mathfrak{sl}(2, \mathbb{R})$, by its restriction to $\mathfrak{sl}(2, \mathbb{R}) \setminus \mathcal{N}$ and its wave front set.

From the preceding results we obtain this new characterization of Spf :

Theorem 6.2. Let $\phi \in \mathcal{C}^{-\infty}\left(\mathfrak{sl}(2, \mathbb{R}), \bigoplus_{k=0}^n S^k(\mathfrak{so}(2n, \mathbb{R})^*) \otimes \Lambda(\mathfrak{g}_1^*)\right)^{\mathfrak{sl}(2, \mathbb{R})}$ such that:

- (i) for $X \in \mathfrak{sl}(2, \mathbb{R}) \setminus \mathcal{N}$, $\phi(X) = \text{Spf}(X) \in \bigoplus_{k=0}^n S^k(\mathfrak{so}(2n, \mathbb{R})^*) \otimes \Lambda(\mathfrak{g}_1^*)$;
- (ii) $\Omega\phi = 0$.

Then we have $\phi = \text{Spf}$.

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